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1 Modeling of dynamics of industrial robots with flexible electric drives*Kostin, G.V.; Steinbach, M.C.; Bock, H.G.; Longman, R.W.;*

Control of Oscillations and Chaos, 1997. Proceedings., 1997 1st International Conference , Volume: 2 , 27-29 Aug. 1997

Pages:275 - 278 vol.2

IEEE CNF

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1 An integrated friction model structure with improved presliding behavior for accurate friction compensation*Swevers, J.; Al-Bender, F.; Ganseman, C.G.; Projogo, T.;*

Automatic Control, IEEE Transactions on , Volume: 45 , Issue: 4 , April 2000

Pages:675 - 686

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Robotics and Automation, IEEE Transactions on , Volume: 12 , Issue: 4 , Aug. 1996

Pages:627 - 633

IEEE JNL

2 Realistic robot simulation: multiple instantiating of robot controller software*Vollmann, K.;*

Industrial Technology, 2002. IEEE ICIT '02. 2002 IEEE International Conference

on , Volume: 2 , 11-14 Dec. 2002

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